```
//EFD_AB_I200_T200_O100_G200_F400//

t0=0
t=t0:0.1:1500
s0=[2.0e-7;2.0e-7;0;0;1.0e-7;0;0;2.0e-7;0;0;4.0e-7;0;0;0;0;0;0;0 ;
0;0;1.0e-7;0;0;2.0e-7;0;0;4.0e-7;0;0;0;0;0;0;0]

ks=5e4
kf=2e6
krf=10

function sfunc = sdot(t,s)
 sfunc(1) = -ks*s(1)*s(2)+ks*s(3)*s(4)
 sfunc(2) = -ks*s(1)*s(2)+ks*s(3)*s(4)
 sfunc(3) = ks*s(1)*s(2)-ks*s(3)*s(4)-kf*s(3)*s(11)+krf*s(18)-
ks*s(3)*s(9)+ks*s(19)*s(20)
 sfunc(4) = ks*s(1)*s(2)-ks*s(3)*s(4)-kf*s(4)*s(5)-
ks*s(4)*s(8)+ks*s(9)*s(10)+ks*s(10)*s(11)-ks*s(4)*s(12)-
kf*s(4)*s(10)+krf*s(17)
 sfunc(5) = -kf*s(4)*s(5)
 sfunc(6) = kf*s(4)*s(5)
 sfunc(7) = kf*s(4)*s(5)
 sfunc(8) = -ks*s(4)*s(8)+ks*s(9)*s(10)-kf*s(8)*s(9)+krf*s(13)-
kf*s(8)*s(11)+krf*s(16)
 sfunc(9) = ks*s(4)*s(8)-ks*s(9)*s(10)-kf*s(8)*s(9)+krf*s(13)-
kf*s(9)*s(12)+krf*s(15)-ks*s(3)*s(9)+ks*s(19)*s(20)
 sfunc(10) = ks*s(4)*s(8)-ks*s(9)*s(10)-
ks*s(10)*s(11)+ks*s(4)*s(12)-kf*s(4)*s(10)+krf*s(17)
 sfunc(11) = -ks*s(10)*s(11)+ks*s(4)*s(12)-kf*s(11)*s(12)+krf*s(14)-
kf*s(8)*s(11)+krf*s(16)-kf*s(3)*s(11)+krf*s(18)
 sfunc(12) = -ks*s(4)*s(12)-ks*s(10)*s(11)-kf*s(11)*s(12)+krf*s(14)-
kf*s(9)*s(12)+krf*s(15)
 sfunc(13) = kf*s(8)*s(9)-krf*s(13)
 sfunc(14) = kf*s(11)*s(12)-krf*s(14)
 sfunc(15) = kf*s(9)*s(12)-krf*s(15)
 sfunc(16) = kf*s(8)*s(11)-krf*s(16)
 sfunc(17) = kf*s(4)*s(10)-krf*s(17)
 sfunc(18) = kf*s(3)*s(11)-krf*s(18)

 sfunc(19) = ks*s(3)*s(9)-ks*s(19)*s(20)-kf*s(19)*s(27)+krf*s(34)-
ks*s(19)*s(25)
 sfunc(20) = ks*s(3)*s(9)-ks*s(19)*s(20)-kf*s(20)*s(21)-
ks*s(20)*s(24)+ks*s(25)*s(26)+ks*s(26)*s(27)-ks*s(20)*s(28)-
kf*s(20)*s(26)+krf*s(33)
 sfunc(21) = -kf*s(20)*s(21)
 sfunc(22) = kf*s(20)*s(21)
 sfunc(23) = kf*s(20)*s(21)
 sfunc(24) = -ks*s(20)*s(24)+ks*s(25)*s(26)-
kf*s(24)*s(25)+krf*s(29)-kf*s(24)*s(27)+krf*s(32)
 sfunc(25) = ks*s(20)*s(24)-ks*s(25)*s(26)-kf*s(24)*s(25)+krf*s(29)-
kf*s(25)*s(28)+krf*s(31)-ks*s(19)*s(25)
 sfunc(26) = ks*s(20)*s(24)-ks*s(25)*s(26)-
ks*s(26)*s(27)+ks*s(20)*s(28)-kf*s(20)*s(26)+krf*s(33)
 sfunc(27) = -ks*s(26)*s(27)+ks*s(20)*s(28)-
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```
kf*s(27)*s(28)+krf*s(30)-kf*s(24)*s(27)+krf*s(32)-
kf*s(19)*s(27)+krf*s(34)
 sfunc(28) = -ks*s(20)*s(28)-ks*s(26)*s(27)-
kf*s(27)*s(28)+krf*s(30)-kf*s(25)*s(28)+krf*s(31)
 sfunc(29) = kf*s(24)*s(25)-krf*s(29)
 sfunc(30) = kf*s(27)*s(28)-krf*s(30)
 sfunc(31) = kf*s(25)*s(28)-krf*s(31)
 sfunc(32) = kf*s(24)*s(27)-krf*s(32)
 sfunc(33) = kf*s(20)*s(26)-krf*s(33)
 sfunc(34) = kf*s(19)*s(27)-krf*s(34)

endfunction

s=ode("rkf",s0,t0,t,sdot)
plot2d(t,s(7,:),1)
plot2d(t,s(23,:),2)

temp=cat(1,t,s)
csvWrite(temp,"EFD_AB.csv")

stacksize('max')
```